A review of the review paper Airy Processes and Variational Formulas

by Jeremy Quastel and Daniel Remenik

Airy Processes

- Fundamental (but new!) random processes on \mathbb{R} (i.e. $x \mapsto \mathcal{A}(x)$ a random process)
- Are believed to govern the long time, large scale spatial fluctuations of random growth models in the *KPZ universality class*
- We will describe them through two models: *last passage percolation* and *the stochastic heat equation*

- Maximum of *correlated* random variables
- Input is iid random variables $\omega_{i,j}$ for $(i,j) \in \mathbb{N}^2$





- For $\omega_{i,j} \sim \text{Geometric}(q)$ the model becomes *integrable*
- Is a formula for the **exact** distribution of $L^{point}(M, N)$





- For $\omega_{i,j} \sim \text{Geometric}(q)$ the model becomes *integrable*
- Is a formula for the **exact** distribution of $L^{point}(M, N)$
- Goes through the Robinson-Schensted-Knuth (RSK) bijection
- Deterministic, combinatorial bijection from arrays of non-negative integers to pairs of semi-standard Young tableaux with the same shape
- Length of top row of the shape is $L^{\text{point}}(M, N)$

- For $\omega_{i,j} \sim \text{Geometric}(q)$ the induced measure on the shape is **Schur measure**
- Can study statistics of the shape using Schur functions (a special family of polynomials that are a basis for the space of symmetric polynomials of a given degree)
- Representation of Schur functions via determinants (Jacobi-Trudi identities) leads to representation of probabilities in terms of determinants

• Distribution of the passage time:

$$\mathbb{P}\left(L^{\text{point}}(M,N) \le n - N + 1\right) = \det(I - K)_{\ell^2\{n+1,n+2,\dots\}}$$

where $K : \mathbb{N}_0 \times \mathbb{N}_0 \to \mathbb{R}$ is given by

$$K(u,v) = \frac{\gamma_{N-1} p_N(u) p_{N-1}(v) - p_{N-1}(u) p_N(v)}{\gamma_N} \sqrt{w(u) w(v)}$$

with $w : \mathbb{N}_0 \to \mathbb{R}$ given by

$$w(k) = q^k \binom{k+M-N}{M-N}$$

and $p_N : \mathbb{N}_0 \to \mathbb{R}$ is the *degree* n *monic orthogonal polynomial* with respect to the weight w, and γ_N its L^2 norm

• Asymptotic statistics of the passage time:

$$\mu_q := 2 \frac{\sqrt{q} + q}{1 - q}, \quad \sigma_q := \frac{q^{1/6} (1 + \sqrt{q})^{4/3}}{1 - q}$$

• Strong Law:

$$\frac{1}{N}L^{\text{point}}(N,N) \xrightarrow[N \to \infty]{a.s.} \mu_q$$

• Fluctuations:

$$\frac{L^{\text{point}}(N,N) - \mu_q N}{\sigma_q N^{1/3}} \xrightarrow[N \to \infty]{(d)} \text{Tracy-Widom GUE distribution}$$

Tracy-Widom GUE Distribution

Probability distribution with CDF

$$F_{\rm GUE}(s) = \det(I - P_s K_{\rm Ai} P_s)_{L^2(\mathbb{R})}$$

where P_s is projection onto the interval (s, ∞) , and K_{Ai} is the Airy kernel (matrix)

$$K_{\mathrm{Ai}}(x,y) = \int_0^\infty \mathrm{Ai}(x+\lambda)\mathrm{Ai}(y+\lambda)d\lambda$$



 \bullet Can turn this into a process by looking at the passage time at points "near" (N,N)



- How near is near?
- \bullet Turns out to be scale $N^{2/3}$ away from (N,N)

 \bullet Can turn this into a process by looking at the passage time at points "near" (N,N)



$$L^{\text{point}}(N+u, N-u) := c_1 N + c_2 N^{1/3} H_N^{\text{point}}(c_3 N^{-2/3} u)$$

Process of Passage Times



• Theorem: [Joh03]

$$H_N^{\text{point}}(u) \xrightarrow[N \to \infty]{(d)} \mathcal{A}_2(u) - u^2$$

as a process in u (in the topology of uniform convergence of continuous functions on compact sets)

• Properties:

- the process $u \mapsto \mathcal{A}_2(u)$ is *stationary*
- its one-point distributions are Tracy-Widom GUE

• there is a formula (in fact several) for the multi-point distributions of \mathcal{A}_2 , i.e.

$$\mathbb{P}\left(\mathcal{A}_2(u_1) \leq x_1, \dots \mathcal{A}_2(u_n) \leq x_n\right)$$

• Theorem: [Joh03]

$$H_N^{\text{point}}(u) \xrightarrow[N \to \infty]{(d)} \mathcal{A}_2(u) - u^2$$

as a process in u (in the topology of uniform convergence of continuous functions on compact sets)

• Properties:

- the process $u \mapsto \mathcal{A}_2(u)$ is *stationary*
- its one-point distributions are Tracy-Widom GUE
- Next time: a formula for

 $\mathbb{P}(\mathcal{A}_2(u) \leq g(u) \text{ for all } u \in [r, l])$

- Some variants of the passage times are integrable
- Can be described by modifying initial conditions





- Some variants of the passage times are integrable
- Can be described by modifying initial conditions



$$L^{\text{flat}}(N+u, N-u) := c_1 N + c_2 N^{1/3} H_N^{\text{line}}(c_3 N^{-2/3} u)$$

• **Theorem:** [Borodin-Ferrari-Pr" *a*hofer-Sasamoto]

$$H_N^{\text{line}}(u) \xrightarrow[N \to \infty]{(d)} \mathcal{A}_1(u)$$

in the sense of convergence of finite-dimensional distributions

• Properties:

- the process $u \mapsto \mathcal{A}_1(u)$ is *stationary*
- its one-point distributions are Tracy-Widom GOE

• there is a formula (in fact several) for the multi-point distributions of \mathcal{A}_1 , i.e.

$$\mathbb{P}\left(\mathcal{A}_1(u_1) \le x_1, \dots, \mathcal{A}_1(u_n) \le x_n\right)$$

- Some variants of the passage times are integrable
- Stationary version: boundary a 2-sided random walk





- Some variants of the passage times are integrable
- Stationary version: boundary a 2-sided random walk



$$L^{\text{stat}}(N+u, N-u) := c_1 N + c_2 N^{1/3} H_N^{\text{stat}}(c_3 N^{-2/3} u)$$

• **Theorem:** [Borodin-Ferrari-Pr" *a*hofer]

$$H_N^{\text{stat}}(u) \xrightarrow[N \to \infty]{(d)} \mathcal{A}_{\text{stat}}(u)$$

in the sense of convergence of finite-dimensional distributions

• Properties:

• the process $u \mapsto \mathcal{A}_1(u)$ is **not** stationary

 \bullet $\mathcal{A}_{\rm stat}$ is a double-sided Brownian motion with a random height shift at the origin

- Can also mix boundary conditions
- The corner-flat process



$$L^{\text{half-line}}(N+u, N-u) = c_1 N + c_2 N^{1/3} H_N^{\text{half-line}}(c_3 N^{-2/3} u)$$

• Theorem: [Borodin-Ferrari-Sasamoto]

$$H_N^{\text{half-line}}(u) - u^2 \mathbf{1} \{ u \ge 0 \} \xrightarrow[N \to \infty]{(d)} \mathcal{A}_{2 \to 1}(u)$$

in the sense of convergence of finite-dimensional distributions

• Properties:

- the process $u \mapsto \mathcal{A}_{2 \to 1}(u)$ is **not** stationary
- one-point distribution of $\mathcal{A}_{2\rightarrow 1}(x)$ is known

•
$$\mathcal{A}_{2\to 1}(u+v) \to \mathcal{A}_2(u)$$
 as $v \to \infty$

•
$$\mathcal{A}_{2\rightarrow 1}(u+v) \rightarrow 2^{1/3}\mathcal{A}_1(2^{-2/3}u)$$
 as $v \rightarrow -\infty$

- Can also mix boundary conditions
- The flat-stat process



 $L^{\text{flat-stat}}(N+u, N-u) = c_1 N + c_2 N^{1/3} H_N^{\text{flat-stat}}(c_3 N^{-2/3} u)$

• **Theorem:** (I think)

$$H_N^{\text{flat-stat}}(u) \xrightarrow[N \to \infty]{(d)} \mathcal{A}_{1 \to \text{BM}}(u)$$

in the sense of convergence of finite-dimensional distributions

• Properties:

- the process $u \mapsto \mathcal{A}_{1 \to BM}(u)$ is **not** stationary
- one-point distribution of $\mathcal{A}_{1 \rightarrow BM}(x)$ is known

•
$$\mathcal{A}_{1 \to BM}(u+v) \to \mathcal{A}_{stat}(u)$$
 as $v \to \infty$

•
$$\mathcal{A}_{1 \to BM}(u+v) \to \mathcal{A}_1(u)$$
 as $v \to -\infty$

- Can also mix boundary conditions
- The corner-stat process



$$L^{\text{corner-stat}}(N+u, N-u) = c_1 N + c_2 N^{1/3} H_N^{\text{corner-stat}}(c_3 N^{-2/3} u)$$

• Theorem: (I think)

$$H_N^{\text{corner-stat}}(u) - u^2 \mathbf{1} \{ u \le 0 \} \xrightarrow[N \to \infty]{(d)} \mathcal{A}_{2 \to \text{BM}}(u)$$

in the sense of convergence of finite-dimensional distributions

• Properties:

- the process $u \mapsto \mathcal{A}_{2 \to BM}(u)$ is **not** stationary
- one-point distribution of $\mathcal{A}_{2 \rightarrow BM}(x)$ is known

•
$$\mathcal{A}_{2\to BM}(u+v) \to \mathcal{A}_{stat}(u)$$
 as $v \to \infty$

•
$$\mathcal{A}_{2 \to BM}(u+v) \to \mathcal{A}_2(u)$$
 as $v \to -\infty$

Airy Processes

- In a sense, the A_2 process is the "fundamental" process and all other processes can be derived from it (at least their one-point distributions)
- Follows because general initial conditions are a superposition of corner initial conditions

• Example:

$$L^{\text{line}}(N) = \max_{k=-N,\dots,N} L^{\text{point}}(N+k,N-k)$$

Translated into scaling limits this becomes

$$\mathcal{A}_1(x) = \sup_{x \in \mathbb{R}} \left\{ \mathcal{A}_2(x) - x^2 \right\}$$

 Variational formula relation between different processes can be understood in terms of the stochastic heat equation

$$\partial_t Z = \frac{1}{2} \partial_{xx} Z + WZ, \quad Z(0,x) = \delta_0(x)$$

where *W* is *space-time white noise*

• Without the noise term the solution is

$$\varrho(t,x) = e^{-x^2/2t}\sqrt{2\pi t}$$

 Variational formula relation between different processes can be understood in terms of the stochastic heat equation

$$\partial_t Z = \frac{1}{2} \partial_{xx} Z + WZ, \quad Z(0, x) = \delta_0(x)$$

where *W* is *space-time white noise*

• With the noise term the solution is $\varrho(t,x)$ times a stationary process

$$Z(t,x) = \varrho(t,x)e^{-t/24} \exp\left\{t^{1/3}A_t(t^{-2/3}x)\right\}$$

- Conjecture: $A_t(x) \rightarrow \mathcal{A}_2(x)$ as $t \rightarrow \infty$, on the process level
- Known for the one-dimensional distributions

Now use that solution is linear in the initial data

$$\partial_t Z_{\mathrm{f}} = \frac{1}{2} \partial_{xx} Z_{\mathrm{f}} + W Z_{\mathrm{f}}, \quad Z_{\mathrm{f}}(0, x) = 1$$

• On the one hand, we can define

$$Z_{\rm f}(t,x) = e^{-t/24} \exp\left\{t^{1/3} A_t^{\rm flat}(t^{-2/3}x)\right\}$$

and we expect that $A_t^{\text{flat}}(x) \to \mathcal{A}_1(x)$. On the other hand

$$Z_{\rm f}(t,x) =: \int \varrho(t,x-y) e^{-t/24} \exp\left\{t^{1/3} A_t(t^{-2/3}(x-y))\right\} dy$$

Steepest descent type heuristic suggests

$$t^{1/3}A_t^{\text{flat}}(t^{-2/3}x) \sim \sup_{y \in \mathbb{R}} \left\{ \log \varrho(t, x - y) + t^{1/3}A_t(t^{-2/3}(x - y)) \right\}$$

Now use that solution is linear in the initial data

$$\partial_t Z_{\mathrm{f}} = \frac{1}{2} \partial_{xx} Z_{\mathrm{f}} + W Z_{\mathrm{f}}, \quad Z_{\mathrm{f}}(0, x) = 1$$

• On the one hand, we can define

$$Z_{\rm f}(t,x) = e^{-t/24} \exp\left\{t^{1/3} A_t^{\rm flat}(t^{-2/3}x)\right\}$$

and we expect that $A_t^{\text{flat}}(x) \to \mathcal{A}_1(x)$. On the other hand

$$Z_{\rm f}(t,x) =: \int \varrho(t,x-y) e^{-t/24} \exp\left\{t^{1/3} A_t(t^{-2/3}(x-y))\right\} dy$$

Using statistical scaling properties one gets

$$t^{1/3}A_t^{\text{flat}}(t^{-2/3}x) \sim \sup_{y \in \mathbb{R}} \left\{ \log \varrho(t, x - y) + t^{1/3}A_t(t^{-2/3}(x - y)) \right\}$$

Now use that solution is linear in the initial data

$$\partial_t Z_{\mathrm{f}} = \frac{1}{2} \partial_{xx} Z_{\mathrm{f}} + W Z_{\mathrm{f}}, \quad Z_{\mathrm{f}}(0, x) = 1$$

• On the one hand, we can define

$$Z_{\rm f}(t,x) = e^{-t/24} \exp\left\{t^{1/3} A_t^{\rm flat}(t^{-2/3}x)\right\}$$

and we expect that $A_t^{\text{flat}}(x) \to \mathcal{A}_1(x)$. On the other hand

$$Z_{\rm f}(t,x) =: \int \varrho(t,x-y) e^{-t/24} \exp\left\{t^{1/3} A_t(t^{-2/3}(x-y))\right\} dy$$

Using statistical scaling properties one gets

$$A_t^{\text{flat}}(x) \sim \sup_{y \in \mathbb{R}} \left\{ -(x-y)^2 + A_t(x-y) \right\}$$

Now use that solution is linear in the initial data

$$\partial_t Z_{\mathrm{f}} = \frac{1}{2} \partial_{xx} Z_{\mathrm{f}} + W Z_{\mathrm{f}}, \quad Z_{\mathrm{f}}(0, x) = 1$$

• On the one hand, we can define

$$Z_{\rm f}(t,x) = e^{-t/24} \exp\left\{t^{1/3} A_t^{\rm flat}(t^{-2/3}x)\right\}$$

and we expect that $A_t^{\text{flat}}(x) \to \mathcal{A}_1(x)$. On the other hand

$$Z_{\rm f}(t,x) =: \int \varrho(t,x-y) e^{-t/24} \exp\left\{t^{1/3} A_t(t^{-2/3}(x-y))\right\} dy$$

Using statistical scaling properties one gets

$$A_t^{\text{flat}}(x) \sim \sup_{y \in \mathbb{R}} \left\{ -(x-y)^2 + A_t(x-y) \right\}$$

Now use that solution is linear in the initial data

$$\partial_t Z_{\mathrm{f}} = \frac{1}{2} \partial_{xx} Z_{\mathrm{f}} + W Z_{\mathrm{f}}, \quad Z_{\mathrm{f}}(0, x) = 1$$

• On the one hand, we can define

$$Z_{\rm f}(t,x) = e^{-t/24} \exp\left\{t^{1/3} A_t^{\rm flat}(t^{-2/3}x)\right\}$$

and we expect that $A_t^{\text{flat}}(x) \to \mathcal{A}_1(x)$. On the other hand

$$Z_{\rm f}(t,x) =: \int \varrho(t,x-y) e^{-t/24} \exp\left\{t^{1/3} A_t(t^{-2/3}(x-y))\right\} dy$$

• Now taking $t \to \infty$ one gets

$$\mathcal{A}_1(x) \stackrel{(d)}{=} \sup_{y \in \mathbb{R}} \left\{ -(x-y)^2 + \mathcal{A}_2(x-y) \right\}$$

$$\mathbb{P}(\mathcal{A}_2(u) \le g(u) \text{ for all } u \in [l, r])$$

• Simplifications:

• can take [l, r] = [0, r - l] = [0, T] by stationarity of \mathcal{A}_2

 \bullet can replace g with $\hat{g}(t) = g(l+r-t)$ by invariance of \mathcal{A}_2 under $u \mapsto -u$

• There are formulas for

$$\mathbb{P}(\mathcal{A}_2(u_1) \le x_1, \dots, \mathcal{A}_2(u_n) \le x_n)$$

expressed in terms of Fredholm determinants

Recall the Tracy-Widom GUE distribution has CDF

$$F_{\rm GUE}(s) = \det(I - P_s K_{\rm Ai} P_s)_{L^2(\mathbb{R})}$$

where P_s is projection onto the interval (s, ∞) , and K_{Ai} is the Airy kernel (matrix)

$$K_{\mathrm{Ai}}(x,y) = \int_0^\infty \mathrm{Ai}(x+\lambda)\mathrm{Ai}(y+\lambda)d\lambda$$



Recall the Tracy-Widom GUE distribution has CDF

$$F_{\rm GUE}(s) = \det(I - P_s K_{\rm Ai} P_s)_{L^2(\mathbb{R})}$$

where P_s is projection onto the interval (s, ∞) , and K_{Ai} is the Airy kernel (matrix)

$$K_{\mathrm{Ai}}(x,y) = \int_0^\infty \mathrm{Ai}(x+\lambda)\mathrm{Ai}(y+\lambda)d\lambda$$

• Ai(x) solves HAi = 0, where $H = -\partial_x^2 + x$ is the *Airy Hamiltonian*, boundary condition is Ai(x) $\rightarrow 0$ as $x \rightarrow \infty$

$$H\operatorname{Ai}(\cdot + \lambda) = -\lambda\operatorname{Ai}(\cdot + \lambda)$$

so K_{Ai} is projection onto the negative eigenspace of H

Recall the Tracy-Widom GUE distribution has CDF

$$F_{\rm GUE}(s) = \det(I - P_s K_{\rm Ai} P_s)_{L^2(\mathbb{R})}$$

where P_s is projection onto the interval (s, ∞) , and K_{Ai} is the Airy kernel (matrix)

$$K_{\mathrm{Ai}}(x,y) = \int_0^\infty \mathrm{Ai}(x+\lambda)\mathrm{Ai}(y+\lambda)d\lambda$$

- Also, think of everything as matrices
 - K_{Ai} is a matrix determined by the Airy function

• $P_sK_{\rm Ai}P_s$ is the lower $[s,\infty)\times[s,\infty)$ block of the $K_{\rm Ai}$ matrix, zero elsewhere

- \bullet OK fine, it's a matrix, so what does \det mean?
- Defn: If K is an integral operator on $L^2(X, d\mu)$ with kernel K(x, y), i.e.

$$(Kf)(x) = \int K(x,y)f(y) \, d\mu(y)$$

then by definition

$$\det(I+\lambda K) = 1 + \sum_{n=1}^{\infty} \frac{\lambda^n}{n!} \int_X \dots \int_X \det[K(x_i, x_j)]_{i,j=1}^n d\mu(x_1) \dots d\mu(x_n)$$

• Why?

• It holds in finite dimensions too!

• Let K be an $n \times n$ matrix

$$\lambda \mapsto \det(I + \lambda K) = \sum_{k=0}^{n} a_k \lambda^k$$

is a degree n polynomial in λ

•
$$a_k = \frac{1}{k!} \partial^k_\lambda \det(I + \lambda K)$$

• Use that the determinant is a linear function of each of its columns, so if $M(\lambda) = [M_1(\lambda)|M_2(\lambda)| \dots |M_n(\lambda)]$ then

$$\det M(\lambda + \epsilon) = \det [M_1(\lambda) + \epsilon \partial_{\lambda} M_1(\lambda)] \dots [M_n(\lambda) + \epsilon \partial_{\lambda} M_n(\lambda)] + O(\epsilon^2)$$
$$= \det M(\lambda) + \epsilon \sum_{k=1}^n \det [M_1(\lambda)] \dots [\partial_{\lambda} M_k(\lambda)] \dots [M_n(\lambda)]$$

• Let K be an $n \times n$ matrix

$$\lambda \mapsto \det(I + \lambda K) = \sum_{k=0}^{n} a_k \lambda^k$$

is a degree n polynomial in λ

•
$$a_k = \frac{1}{k!} \partial^k_\lambda \det(I + \lambda K)$$

• Use that the determinant is a linear function of each of its columns, so if $M(\lambda) = [M_1(\lambda)|M_2(\lambda)| \dots |M_n(\lambda)]$ then

$$\partial_{\lambda} \det M(\lambda) = \sum_{k=1}^{n} \det[M_1(\lambda)| \dots |\partial_{\lambda}M_k(\lambda)| \dots |M_n(\lambda)]$$

 $\partial_{\lambda}(I + \lambda K)_k = K_k$

Fredholm Determinants: Simple Example

$$\det(I + \lambda K) = 1 + \sum_{n=1}^{\infty} \frac{\lambda^n}{n!} \int_X \dots \int_X \det[K(x_i, x_j)]_{i,j=1}^n d\mu(x_1) \dots d\mu(x_n)$$

• Take $K(x, y) = \frac{e^{-x^2/2}}{\sqrt{2\pi}}$ on $L^2(\mathbb{R})$

$$\det(I - P_s K P_s) = \int_{-\infty}^s \frac{e^{-x^2/2}}{\sqrt{2\pi}} dx$$

Multipoint Distributions for \mathcal{A}_2

$$\mathbb{P}(\mathcal{A}_2(t_1) \le x_1, \dots, \mathcal{A}_2(t_n) \le x_n) = \det(I - f^{1/2} K_{\mathrm{Ai}}^{\mathrm{ext}} f^{1/2})_{L^2(\{t_1, \dots, t_n\} \times \mathbb{R})}$$

with $f(t_j, x) = \mathbf{1} \{x \ge t_j\}$ and $K_{\mathrm{Ai}}^{\mathrm{ext}}$ the *extended Airy kernel*

Another formula that is more useful for us

$$\det(I - K_{Ai} + \bar{P}_{x_1}e^{(t_1 - t_2)H}\bar{P}_{x_2}e^{(t_2 - t_3)H}\dots\bar{P}_{x_n}e^{(t_n - t_1)H}K_{Ai})_{L^2(\mathbb{R})}$$

with
$$\overline{P}_a f(x) = \mathbf{1} \{x \le a\} f(x)$$
, and $H = -\partial_x^2 + x$

- Want a formula for $\mathbb{P}(\mathcal{A}_2(u) \leq g(u) \text{ for all } u \in [0,T])$
- Take a fine mesh $t_k = k2^{-n}T$ with $k = 0, 1, ..., 2^n$, then take a limit of the above formula as $n \to \infty$
- Clearly easier to do this with the second formula

Multipoint Distributions for \mathcal{A}_2

Another formula that is more useful for us

$$\det(I - K_{Ai} + \bar{P}_{x_1}e^{(t_1 - t_2)H}\bar{P}_{x_2}e^{(t_2 - t_3)H}\dots\bar{P}_{x_n}e^{TH}K_{Ai})_{L^2(\mathbb{R})}$$

with $\overline{P}_a f(x) = \mathbf{1} \{x \le a\} f(x)$, and $H = -\partial_x^2 + x$

- Want a formula for $\mathbb{P}(\mathcal{A}_2(u) \leq g(u) \text{ for all } u \in [0,T])$
- Take a fine mesh $t_k = k2^{-n}T$ with $k = 0, 1, ..., 2^n$, then take a limit of the above formula as $n \to \infty$
- Clearly easier to do this with the second formula
- Take a limit of the operator

$$\bar{P}_{g(t_1)}e^{(t_1-t_2)H}\bar{P}_{g(t_2)}e^{(t_2-t_3)H}\dots e^{(t_{n-1}-t_n)H}\bar{P}_{g(t_n)}$$

Take a limit of the operator

$$\bar{P}_{g(t_1)}e^{(t_1-t_2)H}\bar{P}_{g(t_2)}e^{(t_2-t_3)H}\dots e^{(t_{n-1}-t_n)H}\bar{P}_{g(t_n)}$$

• For t > 0, if we define $u(t, x) = (e^{-tH}f)(x)$ then u solves

$$\partial_t u = -Hu = \partial_x^2 u - xu, \quad u(0, x) = f(x)$$

So if we apply this operator to a function,

• it kills off the function above $g(t_n)$,

• puts that in as an initial condition and solves a heat equation to time $t_n - t_{n-1}$,

• then kills off the solution above $g(t_{n-1})$

• puts that in as an initial condition and solves a heat equation to time $t_{n-1} - t_{n-2}$,

• ... (now simplify and replace g with \hat{g})

Take a limit of the operator

$$\bar{P}_{g(t_1)}e^{(t_1-t_2)H}\bar{P}_{g(t_2)}e^{(t_2-t_3)H}\dots e^{(t_{n-1}-t_n)H}\bar{P}_{g(t_n)}$$

• For t > 0, if we define $u(t, x) = (e^{-tH}f)(x)$ then u solves

$$\partial_t u = -Hu = \partial_x^2 u - xu, \quad u(0, x) = f(x)$$

 \bullet Hence if we let u(t,x) be the solution to

$$\partial_t = -Hu \text{ for } x < g(t), \quad u(0,x) = f(x) \mathbf{1} \{ x < g(0) \},$$

 $u(t,x) = 0 \text{ for } x \ge g(t)$

and let Θ_T^g be the operator which takes $f(\cdot)$ to $u(T, \cdot)$, then

$$\bar{P}_{g(t_1)}e^{(t_1-t_2)H}\bar{P}_{g(t_2)}e^{(t_2-t_3)H}\dots e^{(t_{n-1}-t_n)H}\bar{P}_{g(t_n)}\to\Theta_T^g$$

 $\mathbb{P} \left(\mathcal{A}_{2}(t_{1}) \leq g(t_{1}), \dots, \mathcal{A}_{2}(t_{n}) \leq g(t_{n}) \right) \\
= \det(I - K_{\mathrm{Ai}} + \bar{P}_{g(t_{n})}e^{(t_{1} - t_{2})H} \bar{P}_{g(t_{n-1})}e^{(t_{2} - t_{3})H} \dots \bar{P}_{g(t_{1})}e^{(t_{n} - t_{1})H} K_{\mathrm{Ai}} \right)_{L^{2}(\mathbb{R})}$

Hence we conclude that

 $\mathbb{P}\left(\mathcal{A}_2(u) \le g(u) \text{ for all } u \in [0,T]\right) = \det(I - K_{\mathrm{Ai}} + \Theta_T^g e^{TH} K_{\mathrm{Ai}})$

• Θ_T^g has an integral kernel and it can be computed, i.e.

$$u(T,x) = (\Theta_T^g f)(x) = \int \Theta_T^g(x,y) f(y) \, dy$$

and there is an explicit formula for $\Theta^g_T(x,y)$

 $\mathbb{P} \left(\mathcal{A}_{2}(t_{1}) \leq g(t_{1}), \dots, \mathcal{A}_{2}(t_{n}) \leq g(t_{n}) \right) \\
= \det(I - K_{\mathrm{Ai}} + \bar{P}_{g(t_{n})}e^{(t_{1} - t_{2})H} \bar{P}_{g(t_{n-1})}e^{(t_{2} - t_{3})H} \dots \bar{P}_{g(t_{1})}e^{(t_{n} - t_{1})H} K_{\mathrm{Ai}} \right)_{L^{2}(\mathbb{R})}$

Hence we conclude that

 $\mathbb{P}\left(\mathcal{A}_2(u) \le g(u) \text{ for all } u \in [0,T]\right) = \det(I - K_{\mathrm{Ai}} + \Theta_T^g e^{TH} K_{\mathrm{Ai}})$

• Θ_T^g has an integral kernel and it can be computed

$$\Theta_T^g(x,y) = e^{-Ty + T^3/3} \varrho_T(x,y) \mathbb{P}_{\hat{B}(0)=x,\hat{B}(T)=y-T^2} \left(\hat{B}(s) \le g(s) - s^2 \text{ on } [0,T] \right)$$

where \hat{B} is a Brownian bridge

• Simplest case is clearly $g(t) = m + t^2$ for m > 0

$$\mathbb{P}(\mathcal{A}_2(t) \le m + t^2 \text{ for } -L \le t \le L) = \det(I - K_{\mathrm{Ai}} + \Theta_L e^{2LH} K_{\mathrm{Ai}})$$

with $\Theta_L = \Theta_{[-L,L]}^{g(t)=t^2+m}$

Endpoint Distribution for Geometric LPP



$$L^{\text{point}}(M, N) := \max_{\pi:(0,0)\to(M,N)} \sum_{\mathbf{v}\in\pi} \omega_{\mathbf{v}}$$

• Let $\kappa_N = \operatorname{argmax}_{k=-N...N} L^{\operatorname{point}}(N+k, N-k)$ (rightmost point)

• Then
$$c_3 N^{-1} \kappa_N \xrightarrow{(d)} \operatorname{argmax}_{t \in \mathbb{R}} \{ \mathcal{A}_2(t) - t^2 \}$$

Slides Produced With

Asymptote: The Vector Graphics Language



http://asymptote.sf.net

(freely available under the GNU public license)