Math 6510 - Homework 6

Due in class on $12/9/14$

- 1. Let $T \in \mathcal{T}^k(V)$ and $S \in \mathcal{T}^l(V)$ be tensors on a vector space V with $Alt(S) = 0$. Show that $Alt(T \otimes S) = Alt(S \otimes T) = 0$. This is in Spivak and I sketched how to prove this in class but it is in good exercise in the linear algebra we are using to try to write down a complete proof on your own.
- 2. $\Lambda(M)$ is the vector space of smooth vector fields on M. Let \overline{T} : $\Lambda(M) \times \cdots \times \Lambda(M) \rightarrow$ $C^{\infty}_-(M)$ be a function such that $\bar{T}(V_1,\ldots,fV_i+gV'_i,\ldots,V_k) = f\bar{T}(V_1,\ldots,V_i,\ldots,V_k) +$ $g\overline{T}(V_1,\ldots,V'_i,\ldots,V_k)$. Show that there exists a $T \in \mathcal{T}^k(M)$ with $T = \overline{T}$. In particular, you should show that if V_1, \ldots, V_k and W_1, \ldots, W_k are vector fields with $V_i(x) = W_i(x)$ then $\bar{T}(V_1, \ldots, V_k)(x) = \bar{T}(W_1, \ldots, W_k)(x).$
	- (a) First assume that there is a neighborhood U of x such that $V_i|_U = W_i|_U$. You can use that fact that there is a smooth function $\psi : M \to \mathbb{R}$ with $supp(\psi) \subset U$ and $\psi(x) = 1$.
	- (b) Let E_1, \ldots, E_n be smooth vector fields that are a basis for each tangent space in U. Assume that $V_i(x) = 0$ and show that $T(V_1, \ldots, V_k)(x) = 0$ by using the fact there are smooth functions $f_j : M \to \mathbb{R}$ with $V_i = \sum f_j E_j$ on U.
	- (c) Use (a) and (b) to finish the proof.
- 3. Let β be a k-form on the product manifold $M \times N$. We say that β is tangent to M if $\beta(\ldots,V,\ldots)=0$ when V is tangent to N.

For the product manifold $M \times I$, where I is an interval, let $\pi_I : M \times I \to I$ be the projections to I. If ω is a k-form on $M \times I$ show that there exists a k-form α and a k – 1-form η on $M \times I$ such that

$$
\omega = \alpha + \pi_I^* dt \wedge \eta
$$

with α and η tangent to M.

- 4. Let $G = Isom^+(\mathbb{R}^2)$ be the group of orientation preserving isometries of \mathbb{R}^2 . We will view points in \mathbb{R}^2 as column vectors. If $T \in G$ then T is of the form $T\begin{pmatrix} x \\ y \end{pmatrix}$ \hat{y} $\Big) = A \left(\begin{array}{c} x \\ y \end{array} \right)$ \hat{y} $+\left(\begin{array}{c}a\\b\end{array}\right)$ b \setminus where $A \in SO(2)$. Define vector fields on \mathbb{R}^2 by $V_1 \begin{pmatrix} x \\ y \end{pmatrix}$ \hat{y} $\bigg) = \left(\begin{array}{cc} 0 & 1 \ -1 & 0 \end{array} \right) \left(\begin{array}{c} x \ y \end{array} \right)$ $=\begin{pmatrix} -y \\ -y \end{pmatrix}$ \boldsymbol{x} $\bigg),$ $V_2\left(\begin{array}{c} x \\ y \end{array}\right)$ \hat{y} $= \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ −1 and $V_3\left(\begin{array}{c}x\\y\end{array}\right)$ \hat{y} $=\begin{pmatrix} 0 \\ 1 \end{pmatrix}$ 1). Let $\mathfrak g$ be the vector space spanned by V_1, V_2 and V_3 . That is g is the vector space of vector fields on \mathbb{R}^2 that are linear combinations of the V_i .
	- (a) Given $T \in G$ and $V \in \mathfrak{g}$ show that $T_*V \in \mathfrak{g}$ and therefore $T_* : \mathfrak{g} \to \mathfrak{g}$ is a linear map.
	- (b) Using the V_i as a basis for g write T_* as a 3 \times 3-matrix and show that G is a subgroup of $GL(n)$.